

Panel methods

Aim: Compute incompressible potential flow around a lifting airfoil of general aerodynamic shape. (also thick profiles).

Method:

- Discretize the surface of the airfoil into (straight line) segments (panels).
- Distribute some singularities (vortex, source, dipole) along the surface of the airfoil
- Choose some simple parametrized distribution of the singularities along each panel (e.g., piecewise constant)
s.t. $\Rightarrow$ solution $\propto$ described by N constants.
- Prescribe boundary conditions (flow tangency, Kutta cond.) at N control points
 $\Rightarrow$ system of N algebraic equations for N unknown constants

Recall the problem formulation:

- Incompressible potential flow is governed by the Laplace equation:

$$\nabla^2 \phi = 0 \quad (1)$$

- Boundary conditions:

i) far field: $\vec{u} \rightarrow \vec{u}_\infty$ as $x^2 + y^2 \rightarrow \infty$ (2)

ii) flow tangency: $\vec{n} \cdot \vec{u} = 0$ at airfoil surface (3)

iii) Kutta condition: continuous & finite velocity & pressure at the trailing edge (4)

Panel method:

- 1) Expected form of the solution - superposition of analytical potential flows:

E.g.:

$$\phi = \phi_\infty + \phi_s + \phi_v \quad (5)$$

$\uparrow$ far field $\downarrow$ source distribution along the surface $\uparrow$ vortex distribution along the surface

$$\nabla^2 \phi_\infty = 0, \nabla^2 \phi_s = 0, \nabla^2 \phi_v = 0 \text{ such that } \nabla^2 \phi = 0.$$

a) ϕ_∞ satisfies the far-field condition:

$$\boxed{\phi_\infty = X \cdot \cos \alpha + y \cdot \sin \alpha} \quad (6)$$

$\Rightarrow$ BCs for ϕ_s and ϕ_v :

i) Far field:

$$\phi_s + \phi_v \rightarrow 0 \quad \text{as} \quad x^2 + y^2 \rightarrow \infty \quad (7)$$

ii) Flow tangency:

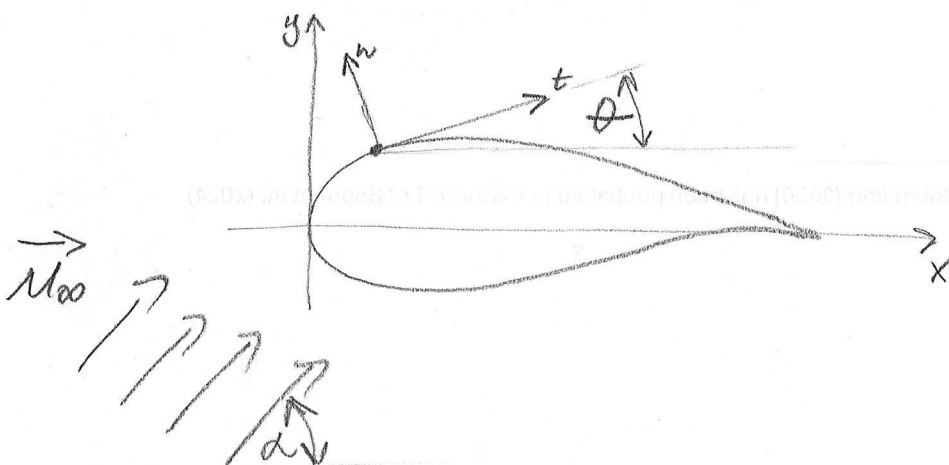
$$u_n \equiv \vec{n} \cdot \vec{u} \equiv \vec{n} \cdot \vec{\nabla} \phi \equiv \frac{\partial \phi_\infty}{\partial n} + \frac{\partial \phi_s}{\partial n} + \frac{\partial \phi_v}{\partial n} \stackrel{!}{=} 0$$

at surface

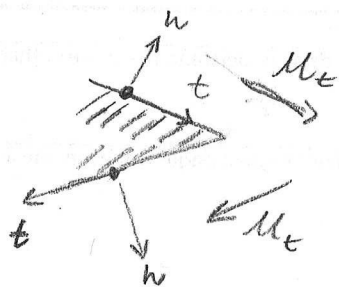
$$\frac{\partial \phi_s}{\partial n} + \frac{\partial \phi_v}{\partial n} \stackrel{!}{=} - \frac{\partial \phi_\infty}{\partial n}$$

$$\frac{\partial \phi_s}{\partial n} + \frac{\partial \phi_v}{\partial n} \stackrel{!}{=} \sin(\theta - \alpha) \quad \text{at surface} \quad (8)$$

where θ is the local inclination of the surface.



iii) Kutta condition



$$-u_e \Big|_{\text{lower surface}} = u_e \Big|_{\text{upper surface}} \quad (9)$$

at trailing edge

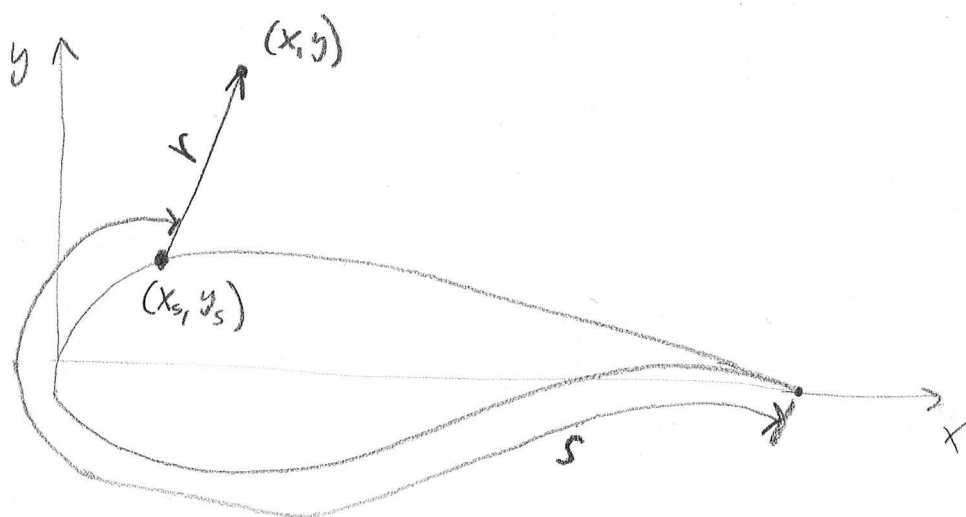
where $u_t = \vec{t} \cdot \vec{u}$

b) ϕ_s as distribution of sources along the surface

$$\phi_s(x, y) = \frac{1}{2\pi} \oint q(x_s(s), y_s(s)) \underbrace{\ln \sqrt{(x-x_s(s))^2 + (y-y_s(s))^2}}_r ds \quad \uparrow \text{arc length}$$

airfoil surface

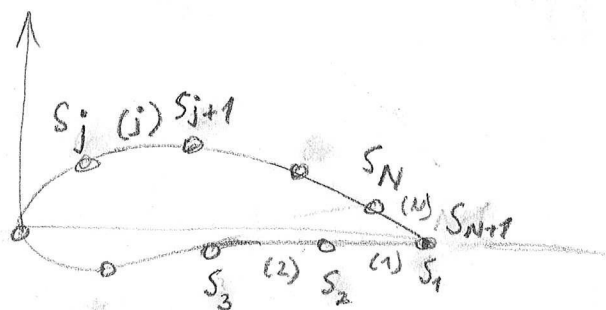
(10)



c) ϕ_v - distribution of vortices along the surface

$$\phi_v(x, y) = -\frac{1}{2\pi} \oint_{\text{airfoil surface}} \gamma(x_s(s), y_s(s)) \arctan \frac{y - y_s(s)}{x - x_s(s)} ds \quad (11)$$

2) Discretize the surface into $N+1$ "nodes" connected by N straight "panels":



a) Select some simple parametrized form of $q(s)$ and $\gamma(s)$.

E.g., piecewise constant:

$$q(s) = q_j, \quad j = 1, \dots, N$$

$$\gamma(s) = \gamma = \text{const.}$$

(Hesse-Smith method)

Different panel methods use different forms of $q(s)$ & $\gamma(s)$

$$b) \phi \approx \sum_{j=1}^N \int_{s_j}^{s_{j+1}} \Rightarrow \phi_s(x, y) \approx \frac{1}{2\pi} \sum_{j=1}^N q_j \int_{s_j}^{s_{j+1}} \ln r \, ds \quad (12)$$

$$\phi_v(x, y) \approx -\frac{\gamma}{2\pi} \sum_{j=1}^N \int_{s_j}^{s_{j+1}} \arctan \frac{y - y_s}{x - x_s} \, ds \quad (13)$$

$$u_s(x,y) = \frac{\partial \phi_s}{\partial x} = \frac{1}{2\pi} \sum_{j=1}^N q_j \int_{s_j}^{s_{j+1}} \frac{x - x_s(s)}{(x - x_s(s))^2 + (y - y_s(s))^2} ds$$

$$v_s(x,y) = \frac{\partial \phi_s}{\partial y} = \frac{1}{2\pi} \sum_{j=1}^N q_j \int_{s_j}^{s_{j+1}} \frac{y - y_s(s)}{(x - x_s(s))^2 + (y - y_s(s))^2} ds$$

$$u_v(x,y) = \frac{\partial \phi_v}{\partial x} = -\frac{\sigma}{2\pi} \sum_{j=1}^N \int_{s_j}^{s_{j+1}} \frac{y - y_s}{(x - x_s)^2 + (y - y_s)^2} ds$$

$$v_v(x,y) = \frac{\partial \phi_v}{\partial y} = \frac{\sigma}{2\pi} \sum_{j=1}^N \int_{s_j}^{s_{j+1}} \frac{x - x_s}{(x - x_s)^2 + (y - y_s)^2} ds$$

$$u = u_{\infty} + u_s + u_v, \quad u_{\infty} = \cos \alpha$$

$$v = v_{\infty} + v_s + v_v, \quad v_{\infty} = \sin \alpha$$

$\theta = \theta_\infty + \theta_s + \theta_v$ determined by $N+1$ parameters:
 $q_1, \dots, q_N$ and μ

3) Discretize flow tangency BC :

- enforce eq. (8) at N discrete control points
 $(\bar{x}_i, \bar{y}_i)$ at the centers of the panels:

$$(\bar{x}_i, \bar{y}_i) = \left(\frac{x_i + x_{i+1}}{2}, \frac{y_i + y_{i+1}}{2} \right) \quad (14)$$

$$\left. \vec{n} \cdot \vec{u}(\bar{x}_i, \bar{y}_i) \stackrel{!}{=} 0 \right|_{i=1, \dots, N} \quad (15)$$

(Kutta condition provides the $N+1$ st eq.)

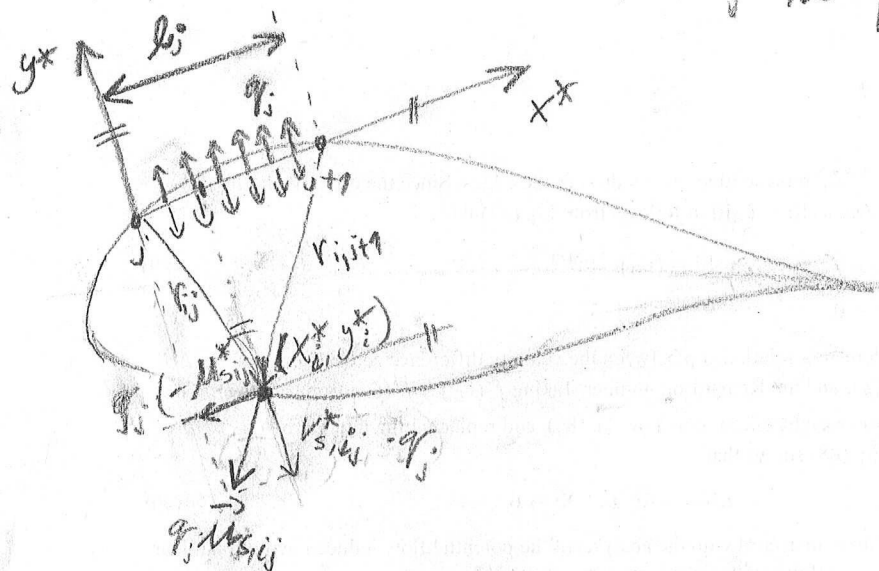
$$\vec{n}_i = (-\sin \theta_i, \cos \theta_i) ; \vec{u} = \vec{u}_\infty + \vec{u}_s + \vec{u}_v$$

$$u_{n,i} \equiv \vec{n}_i \cdot \vec{u}_i = -u_i \sin \theta_i + v_i \cos \theta_i$$

$$\vec{u}_i \equiv \vec{u}(\bar{x}_i, \bar{y}_i) = \vec{u}_\infty(\bar{x}_i, \bar{y}_i) + \vec{u}_s(\bar{x}_i, \bar{y}_i) + \vec{u}_v(\bar{x}_i, \bar{y}_i)$$

$\vec{h} \cdot \vec{u}$ and $\vec{t} \cdot \vec{u}$

$\vec{h} \cdot \vec{u}$ can be expressed analytically in a local coordinate system, oriented with the j -th panel

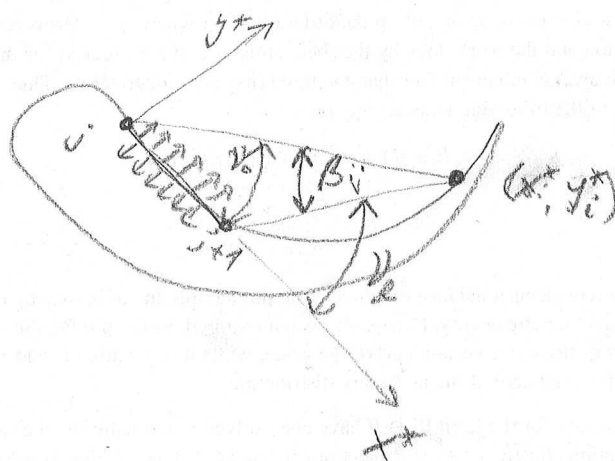


$$u_{sij}^* = \frac{1}{2\pi} \int_0^{l_j} \frac{x_i^* - t}{(x_i^* - t)^2 + y_i^{*2}} dt = -\frac{1}{2\pi} \ln \frac{r_{ij*}}{r_{ij}}$$

Recall: For vortex distribution:

$$u_{vij}^* = v_{sij}^*$$

$$v_{vij}^* = -u_{sij}^*$$



$$v_{sij}^* = \frac{1}{2\pi} \int_0^{l_j} \frac{y_i^*}{(x_i^* - t)^2 + y_i^{*2}} dt$$

$$= \frac{1}{2\pi} \left[\arctan \frac{y_i^*}{x_i^* - t} \right]_{t=0}^{t=l_j}$$

$$= \frac{\beta_{ij}}{2\pi}$$

can be re-arranged with trigon. identity to compute arctan only once :

see Mowar, p. 109, eq. (4-87)

3.5.2025

Flow tangency condition:

$$\vec{n}_i \cdot \vec{u} \stackrel{!}{=} 0 \quad \text{at } (\bar{x}_i, \bar{y}_i)$$

$$\vec{n}_i = (-\sin \theta_i, \cos \theta_i)$$

$$\vec{u} = u \vec{e}_x + v \vec{e}_y = u_j^* \vec{e}_{x_j^*} + v_j^* \vec{e}_{y_j^*}$$

$$\vec{e}_{x_j^*} = (\cos \theta_j, \sin \theta_j) ; \quad \vec{e}_{y_j^*} = (-\sin \theta_j, \cos \theta_j)$$

$$\vec{n}_i \cdot \vec{u}_{ij} = u_{ij}^* \cdot (\vec{n}_i \cdot \vec{e}_{x_j^*}) + v_{ij}^* (\vec{n}_i \cdot \vec{e}_{y_j^*})$$

$$= u_{ij}^* \cdot (-\sin \theta_i \cdot \cos \theta_j + \cos \theta_i \cdot \sin \theta_j)$$

$$+ v_{ij}^* \cdot (+\sin \theta_i \cdot \sin \theta_j + \cos \theta_i \cdot \cos \theta_j)$$

$$= -u_{ij}^* \cdot \sin(\theta_i - \theta_j) + v_{ij}^* \cdot \cos(\theta_i - \theta_j)$$

$$\vec{u} = \vec{u}_\infty + \vec{u}_s + \vec{u}_v$$

$$\vec{u}_i = \vec{u}(\bar{x}_i, \bar{y}_i) = \vec{u}_\infty + \sum_{j=1}^N q_j \vec{u}_{sij} + \rho \sum_{j=1}^N \vec{u}_{vij}$$

$$\vec{u}_\infty = \cos \alpha \vec{e}_x + \sin \alpha \vec{e}_y$$

$$\vec{u}_{sij} = u_{sij}^* \vec{e}_{x_j^*} + v_{sij}^* \vec{e}_{y_j^*}$$

$$\vec{u}_{vij} = u_{vij}^* \vec{e}_{x_j^*} + v_{vij}^* \vec{e}_{y_j^*}$$

$$u_{vij}^* = v_{sij}^*$$

$$v_{vij}^* = -u_{sij}^*$$

Subscripts:

i ... control point

j ... panel with singularity distribution

$$\vec{n}_i \cdot \vec{M}_i = \vec{n}_i \cdot \vec{M}_\infty + \sum_{j=1}^N q_j \vec{M}_{sij} \cdot \vec{n}_i + \mu \sum_{j=1}^N \vec{n}_i \cdot \vec{M}_{vij} \stackrel{!}{=} 0 \quad \text{for } \forall i=1, \dots, N \quad \left[\frac{5.5.2025}{\cdot} \right]$$

$$\vec{n}_i \cdot \vec{M}_\infty = -\sin \theta_i \cdot \cos \alpha + \cos \theta_i \cdot \sin \alpha = -\sin(\theta_i - \alpha)$$

$$\vec{M}_{sij} \cdot \vec{n}_i = \frac{1}{2\pi} \ln \frac{r_{ij+1}}{r_{ij}} \cdot \sin(\theta_i - \theta_j) + \frac{\beta_{ij}}{2\pi} \cos(\theta_i - \theta_j)$$

$$\vec{M}_{vij} \cdot \vec{n}_i = \frac{\beta_{ij}}{2\pi} \cdot (-1) \sin(\theta_i - \theta_j) + \frac{1}{2\pi} \ln \frac{r_{ij+1}}{r_{ij}} \cdot \cos(\theta_i - \theta_j)$$

Linear system of (N) algebraic equations with $N+1$ unknowns:
 $\Rightarrow$ requires the Kutta condition:

$$\vec{t}_1 \cdot \vec{M}_1 + \vec{t}_N \cdot \vec{M}_N \stackrel{!}{=} 0$$

$$\vec{t}_i = (\cos \theta_i, \sin \theta_i) = \vec{e}_x \cos \theta_i + \vec{e}_y \sin \theta_i$$

$$\vec{t}_i \cdot \vec{M}_i = \vec{t}_i \cdot \vec{M}_\infty + \sum_{j=1}^N q_j \vec{M}_{sij} \cdot \vec{t}_i + \mu \sum_{j=1}^N \vec{M}_{vij} \cdot \vec{t}_i$$

$$\vec{t}_i \cdot \vec{M}_\infty = \cos \theta_i \cos \alpha + \sin \theta_i \sin \alpha = \cos(\theta_i - \alpha)$$

$$\begin{aligned} \vec{M}_{sij} \cdot \vec{t}_i &= M_{sij}^* \cdot (\cos \theta_i \cos \theta_j + \sin \theta_i \sin \theta_j) + V_{sij}^* \cdot (-\cos \theta_i \sin \theta_j + \sin \theta_i \cos \theta_j) \\ &= M_{sij}^* \cdot \cos(\theta_i - \theta_j) + V_{sij}^* \cdot \sin(\theta_i - \theta_j) \end{aligned}$$

$$= -\frac{1}{2\pi} \ln \frac{r_{ij+1}}{r_{ij}} \cos(\theta_i - \theta_j) + \frac{\beta_{ij}}{2\pi} \sin(\theta_i - \theta_j)$$

$$\begin{aligned} \vec{M}_{vij} \cdot \vec{t}_i &= M_{vij}^* \cos(\theta_i - \theta_j) + V_{vij}^* \sin(\theta_i - \theta_j) \\ &= \frac{\beta_{ij}}{2\pi} \cos(\theta_i - \theta_j) + \frac{1}{2\pi} \ln \frac{r_{ij+1}}{r_{ij}} \sin(\theta_i - \theta_j) \end{aligned}$$